Conditional Gradients for the Approximately Vanishing Ideal

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Abstract

The vanishing ideal of a set of points $X \subseteq \mathbb{R}^n$ is the set of polynomials that evaluate to 0 over all points $\mathbf{x} \in X$ and admits an efficient representation by a finite set of polynomials called generators. To accommodate the noise in the data set, we introduce the *Conditional Gradients Ap*proximately Vanishing Ideal algorithm (CGAVI) for the construction of the set of generators of the approximately vanishing ideal. The constructed set of generators captures polynomial structures in data and gives rise to a feature map that can, for example, be used in combination with a linear classifier for supervised learning. In CGAVI, we construct the set of generators by solving specific instances of (constrained) convex optimization problems with the Pairwise Frank-Wolfe algorithm (PFW). Among other things, the constructed generators inherit the LASSO generalization bound and not only vanish on the training but also on out-sample data. Moreover, CGAVI admits a compact representation of the approximately vanishing ideal by constructing few generators with sparse coefficient vectors.

Motivation

- Classifier accuracy depends on feature quality
- We study feature transformations for linear kernel *Support Vector Machines* (SVMs) [5]
- High accuracy requires linear separability
- $\bullet \Rightarrow$ achievable via the vanishing ideal

Noisy data

For ease of exposition, we consider the vanishing ideal. In practice, however, data is noisy, and instead of constructing generators of the vanishing ideal, we construct generators of the approximately vanishing ideal.

Vanishing Ideal

Given data set $X = {\mathbf{x}_1, \ldots, \mathbf{x}_m} \subseteq \mathbb{R}^n$,

 $\mathcal{I}_X = \{ f \in \mathbb{R}[x_1, \dots, x_n] \mid f(\mathbf{x}) = 0 \ \forall \mathbf{x} \in X \},\$ the *vanishing ideal*, succinctly characterizes X. By Hilbert's basis theorem [1], there exists a finite number of generators $g_1, \ldots, g_k \in \mathcal{I}_X$, with $k \in \mathbb{N}$, such that for any $f \in \mathcal{I}_X$, there exist $h_1, \ldots, h_k \in \mathbb{R}[x_1, \ldots, x_n]$ such that

$$f = \sum_{i=1}^{k} g_i h_i.$$

Feature transformations with generators

Setting:

• Input space $X \subseteq [-1, 1]^n$

• Output space $\mathcal{Y} = [k]$

• Training sample $S = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)\} \in (\mathcal{X} \times \mathcal{Y})^m \text{ drawn}$ *i.i.d.* from some unknown distribution \mathcal{D}

Goal:

• Determine a hypothesis $h: X \to \mathcal{Y}$ with small generalization error $\mathbb{P}_{(\mathbf{x}, y) \sim \mathcal{D}}[h(\mathbf{x}) \neq y]$

Pipeline:

- Let $X = \{x_1, ..., x_m\}$
- For all $i \in [k]$, let $X^i \subseteq X$ denote the set of feature vectors corresponding to class *i*
- For all $i \in [k]$, construct a set of generators $\mathcal{G}^{i} = \{g_{i}^{(i)}\}_{i=1}^{|\mathcal{G}^{i}|}$ for the vanishing ideal $\mathcal{I}_{X^{i}}$
- Transform samples $\mathbf{x} \in X$ via the feature transformation

$$\mathbf{x} \mapsto \tilde{\mathbf{x}} = \left(\dots, |g_1^{(i)}(\mathbf{x})|, \dots, |g_{|\mathcal{G}^i|}^{(i)}(\mathbf{x})|, \dots\right)^{\mathsf{T}}$$
^[1]

$$\tilde{S} = \{(\tilde{\mathbf{x}}, y) \mid (\mathbf{x}, y) \in S\}$$
 is linearly separable

• Train a linear kernel SVM on \tilde{S}

Open question:

• How to construct the sets of generators \mathcal{G}^i ?



Oracle Approximately Vanishing Ideal algorithm (OAVI)

Algorithm 1 OAVT	
	Explanatio
nput: $X = \{\mathbf{x}_1, \dots, \mathbf{x}_m\} \subseteq \mathbb{R}^n \text{ and } \psi \ge \varepsilon \ge 0.$ Dutput: $\mathcal{G}, \mathcal{O} \subseteq \mathbb{R}[x_1, \dots, x_n].$ 1: $d \leftarrow 1$ 2: $\mathcal{O} = \{t_1\}_{\sigma} \leftarrow \{1\}_{\sigma}$ 3: $\mathcal{G} \leftarrow \emptyset$	 O: set of r G: set of g ∂_dO: term whether the set of g
4: while $\partial_d O = \{u_1, \ldots, u_k\}_{\sigma} \neq \emptyset$ do	• ORACLE: co
5: for $i = 1,, k$ do	constraine
6: $g \leftarrow \text{ORACLE}(X, O, u_i, \varepsilon)$	Properties:
7: if $MSE(g, X) \le \psi$ then	[3], OAVI is
8: $\mathcal{G} \leftarrow \mathcal{G} \cup \{g\}$	• C. containe
9: else	• g contains
10: $O \leftarrow (O \cup \{u_i\})_{\sigma}$	 Generator
11: $d \leftarrow d + 1$	•CGAVI + li

Numerical Experiments

We compare CGAVI to related methods such as the *Approximate Vanishing Ideal algorithm* (AVI) [2] and Vanishing Component Analysis (VCA) [4] as feature transformation techniques for a linear kernel SVM. We also compare the methods to a polynomial kernel SVM.

Algorithms		Data sets								
		bank	cancer	htru2	iris	seeds	sonar	spam	voice	wine
SPAR	CGAVI	0.65	0.54	0.53	0.15	0.13	0.82	0.37	0.36	0.51
	AVI	0.01	0.03	0.02	0.00	0.05	0.02	0.04	0.06	0.03
	VCA	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
Error	CGAVI	0.09	3.42	2.05	4.33	5.95	20.95	5.90	19.80	2.08
	AVI	0.00	3.46	2.11	4.00	4.76	26.43	6.64	23.14	3.33
	VCA	0.00	5.44	2.15	4.17	5.71	31.90	7.13	29.02	3.06
	SVM	0.00	2.72	2.05	3.17	6.79	21.07	7.22	18.43	3.19

Table 1: We compare the *sparsity* of the feature transformation, SPAR, larger SPAR indicating sparser generators, and the classification error on the test set in %, Error. The results are averaged over ten random 60%/40% train/test partitions and the best results in each category are in bold.

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n:

non-leading terms of generators generators

ns of degree d for which OAVI checks hey are leading terms of generators onstructs a polynomial by solving a ed convex optimization problem

When ORACLE is implemented with PFW called CGAVI and

s few and sparse generators rs in \mathcal{G} vanish on out-sample data inear kernel SVM \Rightarrow margin bound

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